A Formal Analysis of Edit Distance

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1 Overview

The edit distance is a means of measuring the cost of transforming one string into another by way of insert, delete and change operators. The theoretical and computational underpinnings of edit distance are discussed in a formal mathematical framework.

2 Preliminaries

Let \( \Sigma \) be a finite nonempty set of symbols. The set of all finite strings with elements from \( \Sigma \) (including the empty string) is \( \Sigma^* \). Strings are naturally functions; the string \( s = s_0s_1\ldots s_k \) is identified with the set of ordered pairs (i.e., function)

\[
s = \{(0, s_0), (1, s_1), \ldots (k, s_k)\}
\]

The domain and range of function \( f \), denoted by \( D_f \) and \( R_f \) respectively, are defined by

\[
D_f = \{x : \exists y, (x, y) \in f\}
\]

\[
R_f = \{y : \exists x, (x, y) \in f\}
\]

The notation

\[
f : A \rightarrow B
\]

asserts that \( f \) is a function whose domain is a subset of \( A \) and whose range is a subset of \( B \). The set \( B \) is referred to as the co-domain, the set \( A \) is referred to as the given-domain. If \( D_f = A \), then \( f \) is called a function from \( A \) to \( B \). If \( D_f \neq A \), then \( f \) is called a partial function from \( A \) to \( B \); for example, every string \( s \in \Sigma^* \) is a partial function \( s : \mathbb{N} \rightarrow \Sigma \), where \( \mathbb{N} \) is the set of nonnegative integers.
The length \(|A|\) of string \(A\) refers to the cardinality of (the set of ordered pairs) \(A\). In particular, the empty string \(\emptyset\) has length \(|\emptyset| = 0\).

The discussion above explains how any given string \(s\) is a function, which in turn is a partial function—call it \(\Phi(s)\)—from \(\mathbb{N}\) to \(\Sigma\). Given string \(s = abc\), for example, \(\Phi(s) = \{(0,a),(1,b),(2,c)\}\) is the naturally associated partial function. Consider reversing this process: let

\[
f = \{(i_0, s_0), (i_1, s_1), \ldots, (i_k, s_k)\}
\]

be a partial function from \(\mathbb{N}\) to \(\Sigma\), where \(i_0 < i_1 < \cdots < i_k\) comprise the domain of \(f\). It is naturally a string, namely \(s_0 s_1 \ldots s_k\); let \(\Psi(f)\) denote this string. Passing from this string to a function in the natural way yields

\[
\Phi(\Psi(f)) = \{(0, s_0), (1, s_1), \ldots, (k, s_k)\}
\]

which is not necessarily the same partial function \(f\) as was began with. The partial function \(\Phi(\Psi(f))\) is called the normal form of \(f\). A partial function \(f : \mathbb{N} \rightarrow \Sigma\) for which \(f = \Phi(\Psi(f))\) is said to be normalized. The following properties are easily verified

1. \(\Psi(\Phi(s)) = s\), for every string \(s \in \Sigma^*\).
2. \(\Phi(\Psi(f)) = f\), for every normalized partial function \(f : \mathbb{N} \rightarrow \Sigma\).

In particular, \(\Phi(s)\) is normalized for every \(s \in \Sigma^*\), and the functions \(\Phi\) and \(\Psi\) formally describe how strings and normalized partial functions can be thought of interchangeably. This paper, however, generalizes the concept of string from normalized partial functions to partial functions; any partial function \(f : \mathbb{N} \rightarrow \Sigma\) will henceforth be called a string, and \(\Psi(f)\) will be called its normal representation.

As previously observed, from the normal representation of string \(f\) it is only the normal form of \(f\) which necessarily may be recovered. For instance, the normal representation of string \(f = \{(3,b),(1,a),(117,c)\}\) is \(abc\), and given \(abc\) it is only the normal form \(\Phi(abc) = \{(1,b),(0,a),(2,c)\}\) of \(f\) which may be recovered.

An edit operation is either a change, insert, or delete operation, and these three types of operations are mutually exclusive. Let \(\mathcal{E}\) be the set of all edit operations. Elements of \(\mathcal{E}\) map strings (i.e., partial functions from \(\mathbb{N}\) to \(\Sigma\)) to strings. Change operators are denoted by \(m \rightarrow b\) where \(m \in \mathbb{N}\) and \(b \in \Sigma\), and are defined by

\[
m \rightarrow b(f) = (f \setminus \{(m,f(m))\}) \cup \{(m,b)\}\text{ if } m \in D_f
\]
Insert operators are denoted by \( m \rightarrow b \) where \( m \in \mathbb{N} \) and \( b \in \Sigma \), and are defined by
\[
m \rightarrow b(f) = f \cup \{(m, b)\} \text{ if } m \notin D_f
\]
Delete operators are denoted by \( m \rightarrow \) where \( m \in \mathbb{N} \), and are defined by
\[
m \rightarrow (f) = f \setminus \{(m, f(m))\} \text{ if } m \in D_f
\]
Note that edit operations are not defined for every string; for example, \( m \rightarrow (f) \) is undefined whenever \( m \notin D_f \). Thus elements of \( \mathcal{E} \) are partial functions from the set of all strings to the set of all strings. When defined, the result of applying an edit operation to a string \( f \) is different from \( f \) except in the case \( m \rightarrow b(f) \) where \((m, b) \in f\). In this case the edit operation (applied to \( f \)) is said to be \textit{trivial}.

Let \( S \) be the set of all finite sequences of edit operations. Elements of \( S \) have the form \( e_1 e_2 \ldots e_n \) where \( e_i \in \mathcal{E} \) and \( n \in \mathbb{N} \) (if \( n = 0 \), the sequence is empty). Elements of \( S \) are called \textit{edit sequences} and may be interpreted as mapping strings to strings:
\[
e_1 e_2 \ldots e_n(f) = e_1(\ldots e_{n-1}(e_n(f))\ldots)
\]
If \( \varepsilon \in S \) is the empty sequence, then \( \varepsilon(f) = f \) for all strings \( f \). Note that because elements of \( \mathcal{E} \) are partial functions, so too are edit sequences; \( e_1 e_2 \ldots e_n(f) \) is not necessarily defined.

**Lemma 1** For every string \( f \), there exists an edit sequence \( s \) such that
\[
s(f) = \emptyset
\]
Proof: If \( f = \emptyset \), then let \( s = \varepsilon \). Otherwise, let \( D_f = \{i_0, \ldots, i_n\} \). Note that
\[
i_0 \rightarrow \ldots i_n \rightarrow (f) = \emptyset.
\]
\( \square \)

**Lemma 2** For every string \( f \), there exists an edit sequence \( s \) such that
\[
s(\emptyset) = f
\]
Proof: If \( f = \emptyset \), then let \( s = \varepsilon \). Otherwise, let \( D_f = \{i_0, \ldots, i_n\} \). Note that
\[
i_0 \rightarrow f(i_0) \ldots i_n \rightarrow f(i_n)(\emptyset) = f.
\]
\( \square \)

**Theorem 3** For all strings \( f \) and \( g \), there exists an edit sequence \( s \) such that \( s(f) = g \).
Proof: Appealing to Lemmas 1 and 2, let \( s_1 \) and \( s_2 \) be edit sequences such that \( s_2(f) = \emptyset \) and \( s_1(\emptyset) = g \). Now let \( s = s_1s_2 \) (i.e., \( s \) is the concatenation of \( s_1 \) and \( s_2 \)). It follows that \( s(f) = s_1(s_2(f)) = g \).

Each type of edit operation has an associated cost. Let \( \gamma_i > 0 \) be the cost of an insert operation, \( \gamma_d > 0 \) be the cost of an delete operation, and \( \gamma_c > 0 \) be the cost of a nontrivial change operation; trivial edit operations have zero cost. Strictly speaking, a change operator does not have a cost; it’s argument is required in order to determine whether it is trivial, in which case it has zero cost. Thus cost is associated with the pair operator and argument, rather than associated with operator alone.

To enable speaking of the cost of an edit sequence (which may contain a potentially trivial change operator) we say that \( s \in S \) takes \( f \) to \( g \) provided \( s(f) = g \). Now the cost \( \gamma(s, f) \) of an edit sequence \( s \) taking \( f \) to \( g \) may be inductively defined as follows

\[
\begin{align*}
\gamma(\varepsilon, f) & = 0 \\
\gamma(m \rightarrow_a f) & = \gamma_d \\
\gamma(m \rightarrow_i b, f) & = \gamma_i \\
\gamma(m \rightarrow_c b, f) & = 0 \text{ if } f = m \rightarrow b(f), \text{ and } \gamma_c \text{ otherwise} \\
\gamma(e_0 \ldots e_n, f) & = \gamma(e_0, e_1 \ldots e_n(f)) + \gamma(e_1 \ldots e_n, f)
\end{align*}
\]

When \( f \) can be inferred from context, \( \gamma(s, f) \) is abbreviated by \( \gamma(s) \). Moreover, to assert that \( s \) is an edit sequence taking \( f \) to \( g \) is to establish a context in which \( \gamma(s, f) \) may be abbreviated by \( \gamma(s) \).

**Theorem 4** Let \( s \) be an edit sequence taking \( f \) to \( h \), and let \( s' \) be an edit sequence taking \( h \) to \( g \). The concatenation \( s'' = s's \) takes \( f \) to \( g \), and

\[
\gamma(s'') = \gamma(s') + \gamma(s)
\]

Proof: Let \( s' = e_0 \ldots e_k \), and let \( s = e_{k+1} \ldots e_n \). Then \( s'' = e_0 \ldots e_n \) and according to the recursive definition for the cost of an edit sequence,

\[
\begin{align*}
\gamma(s'', f) & = \sum_{j=0}^{n} \gamma(e_j, e_{j+1} \ldots e_n(f)) \\
& = \sum_{j=0}^{k} \gamma(e_j, e_{j+1} \ldots e_n(f)) + \sum_{j=k+1}^{n} \gamma(e_j, e_{j+1} \ldots e_n(f)) \\
& = \sum_{j=0}^{k} \gamma(e_j, e_{j+1} \ldots e_k(s(f)) + \gamma(s, f) \\
& = \gamma(s', h) + \gamma(s, f)
\end{align*}
\]
Theorem 5 Let \( s \) be an edit sequence taking \( f \) to \( g \). If \( \gamma_i = \gamma_d \), then there exists an edit sequence \( s' \) taking \( g \) to \( f \) such that \( \gamma(s) = \gamma(s') \). Moreover, \( s' \) may be chosen to have the same length as \( s \).

Proof: Induct on the length of \( s \). Base case: If \( s = \varepsilon \) then \( f = s(f) = g \). Let \( s' = \varepsilon \) and observe that \( \gamma(s) = \gamma(s') = 0 \).

Inductive step: let \( s = e_0 \ldots e_k \), and let \( h = e_1 \ldots e_k(f) \). Since \( s(f) = g \), it follows that \( e_0(h) = g \). By the inductive hypothesis, there exists \( e'_0 \ldots e'_{k-1} \) taking \( h \) to \( f \) such that \( \gamma(e'_0 \ldots e'_{k-1}) = \gamma(e_1 \ldots e_k) \). The proof is completed by showing there exists \( e'_k \) taking \( g \) to \( h \) such that \( \gamma(e'_k) = \gamma(e_0) \). This would suffice because then

\[
s'(g) = e'_0 \ldots e'_{k-1}(e_k(g)) = e'_0 \ldots e'_{k-1}(h) = f
\]

and by theorem 4,

\[
\gamma(s') = \gamma(e'_0 \ldots e'_{k-1}, h) + \gamma(e'_k, g) = \gamma(e_1 \ldots e_k, f) + \gamma(e_0, h) = \gamma(s)
\]

There are three cases to consider, based on the type of edit operation \( e_0 \) is.

Case 1: \( e_0 = m \rightarrow g(m) \) (recall that \( e_0(h) = g \); if \( e_0 \) is a change operator then \( g \) and \( h \) agree everywhere except possibly at \( m \)). Let \( e'_k \) be \( m \rightarrow h(m) \). Note that if \( e_0 \) is trivial, then \( g = h \) and \( e'_k \) is therefore trivial. If \( e_0 \) is nontrivial, then \( h(m) \neq g(m) \) and \( e'_k \) is therefore nontrivial. In either case, \( \gamma(e'_k) = \gamma(e_0) \).

Case 2: \( e_1 = m \rightarrow g(m) \) (if \( e_0 \) is an insert operator, then \( g \) is the disjoint union \( h \cup \{(m, g(m))\} \)). Let \( e'_n \) be \( m \rightarrow \). Since \( \gamma_i = \gamma_d \), \( \gamma(e'_n) = \gamma(e_0) \).

Case 3: \( e_1 = m \rightarrow \) (if \( e_0 \) is a delete operator, then \( h \) is the disjoint union \( g \cup \{(m, h(m))\} \)). Let \( e'_n \) be the edit operation \( m \rightarrow h(m) \). Since \( \gamma_i = \gamma_d \), \( \gamma(e'_k) = \gamma(e_0) \).

\[\square\]

Edit distance is a function \( \delta \) which maps two strings to a nonnegative real, and is defined by

\[
\delta(f, g) = \min\{\gamma(s) \mid s \text{ is an edit sequence taking } f \text{ to } g\}
\]
Given strings $f$ and $g$, the distance from $f$ to $g$ is defined as $\delta(f, g)$. This distance exists, by theorem 3. That this definition is reasonable will now be established.

**Lemma 6** The distance between $f$ and $g$ is nonnegative, and is zero if and only if $f = g$.

Proof: Distance is nonnegative because edit sequences have nonnegative cost. If $f = g$ then $\delta(f, g) = 0$ since $\varepsilon(f) = g$ and $\gamma(\varepsilon) = 0$. Conversely, let $s = e_0 \ldots e_k$ be an edit sequence taking $f$ to $g$ having zero cost. It follows that every edit operator in $s$ must be trivial, since otherwise the sum

$$\gamma(s) = \sum_{j=0}^{k} \gamma(e_j, e_{j+1} \ldots e_k (f))$$

would be positive.

\[\square\]

**Lemma 7** The triangle inequality holds,

$$\delta(f, g) \leq \delta(f, h) + \delta(h, g)$$

Proof: Let $\delta(f, h) = \gamma(s)$ and $\delta(h, g) = \gamma(s')$, where $s(f) = h$ and $s'(h) = g$. Note that the concatenation $s'' = s's$ takes $f$ to $g$, hence $\delta(f, g) \leq \gamma(s'')$. This completes the proof, since by theorem 4, $\gamma(s'') = \gamma(s') + \gamma(s)$.

\[\square\]

**Lemma 8** If $\gamma_i = \gamma_d$, then distance is symmetric,

$$\delta(f, g) = \delta(g, f)$$

Proof: It will be shown that $\delta(f, g) \geq \delta(g, h)$. That would complete the proof, since two applications of the inequality yield

$$\delta(f, g) \geq \delta(g, f) \geq \delta(f, g)$$

Let $\delta(f, g) = \gamma(s)$, where $s$ takes $f$ to $g$. By theorem 5, there exists $s'$ taking $g$ to $f$ such that $\gamma(s') = \gamma(s)$. Hence, $\delta(g, f) \leq \gamma(s') = \gamma(s)$.

\[\square\]

**Theorem 9** Edit distance is a metric if and only if $\gamma_i = \gamma_d$.

Proof: To show the edit distance is a metric, it must be established that
1. \( \delta(f, g) \geq 0 \)
2. \( \delta(f, g) = 0 \iff f = g \)
3. \( \delta(f, h) \leq \delta(f, g) + \delta(g, h) \).
4. \( \delta(f, g) = \delta(g, f) \).

Appealing to the previous lemmas shows the above properties hold when \( \gamma_i = \gamma_d \) (in fact, only symmetry requires \( \gamma_i = \gamma_d \)).

Conversely, suppose property 4 holds. Let \( f = \emptyset \) and \( g = \{ (0, a) \} \). If \( s \) is an edit sequence taking \( f \) to \( g \), then \( s \) must contain an insert edit operation (otherwise \( |s(f)| \leq |f| < |g| \)). Since \( g = 0 \rightarrow a \ (f) \), the distance from \( f \) to \( g \) is \( \gamma_i \). If \( s' \) is an edit sequence taking \( g \) to \( f \), then \( s' \) must contain a delete edit operation (otherwise \( |s'(g)| \geq |g| > |f| \)). Since \( f = 0 \rightarrow (g) \), the distance from \( g \) to \( f \) is \( \gamma_d \). Thus \( \gamma_i = \delta(f, g) = \delta(g, f) = \gamma_d \).

\[ \square \]

3 Traces

A trace is an ordered triple \((p, f, g)\) where \( f, g \) are strings and \( p \) is an increasing (i.e., \( i < j \implies p(i) < p(j) \)) partial function \( p : D_f \rightarrow D_g \). Trace \((p, f, g)\) is referred to as a trace from \( f \) to \( g \).

The cost of trace \( t = (p, f, g) \) is defined as

\[
\gamma(t) = |D_f \setminus D_p| \gamma_a + |D_g \setminus R_p| \gamma_i + \sum_{(i, j) \in p} \gamma(i \rightarrow g(j), f)
\]

Let \( \hat{f} \) denote the normal representation \( \Psi(f) \) of string \( f \). Define an equivalence relation \( \equiv \) on the set of strings by \( f \equiv g \) if and only if \( f = \hat{g} \). Let \([f]\) denote the equivalence class of \( f \).

**Lemma 10** Strings \( f \) and \( g \) are equivalent if and only if there exists an increasing onto function \( \varphi : D_f \rightarrow D_g \) such that \( f = g \circ \varphi \).

**Proof:** Let \( f = \{ (i_0, f_0), \ldots, (i_k, f_k) \} \) and \( g = \{ (j_0, g_0), \ldots, (j_l, g_l) \} \), where \( i_0 < \cdots < i_k \) and \( j_0 < \cdots < j_l \). Suppose \( \varphi \) exists. Since \( \varphi \) is increasing, it is a one-to-one and onto order-preserving map from \( D_f \) to \( D_g \). Hence \( k = l \) and \( \varphi(i_h) = j_h \). Therefore,

\[
f_{h} = f(i_h) = g \circ \varphi(i_h) = g(j_h) = g_{h}
\]

7
Conversely, suppose $f \equiv g$. Then $k = l$ and $f_h = g_h$ for $0 \leq h \leq k$. Let $\varphi(i_h) = j_h$, and note that $\varphi : D_f \to D_g$ is increasing and onto. Moreover,

$$g \circ \varphi(i_h) = g(j_h) = g_h = f_h = f(i_h)$$

$\square$

Note that the function $\varphi$ in lemma 10 is a one-to-one and onto order-preserving function since an increasing function preserves order and must be one-to-one.

**Theorem 11** Let $t$ be a trace from $f$ to $g$. There exists $u \in [f]$, $v \in [g]$, and an edit sequence $s$ taking $u$ to $v$, such that $\gamma(s) = \gamma(t)$.

**Proof:** Let $t = (p, f, g)$. Let $f$ be the string $\{(i_0, f_0), \ldots, (i_k, f_k)\}$ where $i_0 < \cdots < i_k$, and let $g$ be the string $\{(j_0, g_0), \ldots, (j_l, g_l)\}$ where $j_0 < \cdots < j_l$. Let $n$ be an integer greater than $i_k + j_l$, and let $u$ be

$$u = \bigcup_{h=0}^{k} \{(i_h + n(1 + h), f_h)\}$$

Note that $u$ is equivalent to $f$. For the purposes of this proof, let the maximum of an empty collection of integers be $0$, and let $v$ be the disjoint union

$$v = \bigcup_{h : i_h \in D_p} \{(i_h + n(1 + h), g(p(i_h)))\} \cup \bigcup_{h : j_h \in D_g \setminus R_p} \{(j_h + \max\{i_m + n(1 + m) \mid p(i_m) < j_h\}, g_h)\}$$

The union above which is indexed by $h : i_h \in D_p$ (call it the first union) involves mutually disjoint sets because $i_h + n(1 + h)$ is an increasing function of $h$. Similarly, the union above which is indexed by $h : j_h \in D_g \setminus R_p$ (call it the second union) involves mutually disjoint sets. The first union is disjoint from the second union because otherwise there exist $h$ and $h'$ such that

$$i_h + n(1 + h) = j_{h'} + \max\{i_m + n(1 + m) \mid p(i_m) < j_{h'}\}$$

Reducing modulo $n$ gives

$$i_h = \begin{cases} j_{h'} & \text{if } \emptyset = \{m \mid p(i_m) < j_{h'}\} \\ j_{h'} + i_{\max\{m \mid p(i_m) < j_{h'}\}} & \text{otherwise} \end{cases}$$

In the first case above ($\emptyset = \{m \mid p(i_m) < j_{h'}\}$), equation 1 simplifies to $i_h + n(1 + h) = j_{h'}$ which contradicts $i_h = j_{h'}$. Assume therefore that the
second case of equation 2 holds. Substituting for \( i_h \) (as given by equation 2) into equation 1 and canceling \( j_{h'} \) yields

\[
\hat{i}_{\max}(m \mid p(i_m) < j_{h'}) + n(1 + h) = \max \{i_m + n(1 + m) \mid p(i_m) < j_{h'}\} \\
\Rightarrow \quad n(1 + h) = \max \{1 + m \mid p(i_m) < j_{h'}\} \\
\Rightarrow \quad h = \max \{m \mid p(i_m) < j_{h'}\}
\]

Substituting for \( h \) (as given above) into equation 2 gives

\[
\hat{i}_{\max}(m \mid p(i_m) < j_{h'}) = j_{h'} + \hat{i}_{\max}(m \mid p(i_m) < j_{h'}) \\
\Rightarrow \quad j_{h'} = 0 \\
\Rightarrow \quad \emptyset = \{m \mid p(i_m) < j_{h'}\}
\]

contradicting the assumption that the second case of equation 2 holds. Note that \( v \) has been shown to be a function, since no two elements (of \( v \)) have the same first component.

By construction, \( v = g \circ \varphi \) where \( \varphi : D_v \to D_g \) is defined as

\[
\varphi(i_h + n(h + 1)) = p(i_h) \quad \text{for } i_h \in D_p \\
\varphi(j_h + \max \{i_m + n(1 + m) \mid p(i_m) < j_h\}) = j_h \quad \text{for } j_h \in D_g \setminus R_p
\]

Since \( p \) is increasing, it is a one-to-one and onto order-preserving function from \( D_p \) to \( R_p \). Moreover,

\[
D_g = R_p \cup (D_g \setminus R_p) = p(D_p) \cup (D_g \setminus R_p)
\]

Hence \( \varphi \) is onto. By lemma 10, \( v = g \) provided \( \varphi \) is an increasing function. As has already been observed, \( i_h + n(1 + h) \) and \( p(i_h) \) are increasing functions of \( h \). Thus \( \varphi \) is increasing when restricted to the set

\[
A = \{i_h + n(1 + h) \mid i_h \in D_p\}
\]

Similarly, \( \varphi \) is increasing when restricted to

\[
B = \{j_h + \max \{i_m + n(1 + m) \mid p(i_m) < j_h\} \mid j_h \in D_g \setminus R_p\}
\]

Let \( a \in A \) and \( b \in B \). To establish that \( \varphi \) is increasing, it remains to show

\[
a < b \implies \varphi(a) < \varphi(b) \\
b < a \implies \varphi(b) < \varphi(a)
\]

Case 1: \( a = i_h + n(1 + h) < j_{h'} + \max \{i_m + n(1 + m) \mid p(i_m) < j_{h'}\} = b \).
The desired conclusion is \( p(i_h) < j_{h'} \). Note that \( a < b \) is contradicted by \( \emptyset = \{m \mid p(i_m) < j_{h'}\} \) (since \( b \) then simplifies to \( j_{h'} \)). Therefore let \( i_M + n(1 + M) = \max \{i_m + n(1 + m) \mid p(i_m) < j_{h'}\} \). If \( p(i_h) \geq j_{h'} \), then
\( h > M = \max \{ m \mid p(i_m) < j_h \} \). In particular, \( h \geq M + 1 \). This yields the contradiction

\[
a = i_h + n(1 + h) > i_M + n(1 + M + 1) > j_{h'} + i_M + n(1 + M) = b
\]

Case 2: \( b = j_{h'} + \max \{ i_m + n(1 + m) \mid p(i_m) < j_{h'} \} < i_h + n(1 + h) = a \). The desired conclusion is \( j_{h'} < p(i_h) \). If this were not so, then \( j_{h'} > p(i_h) \) (equality is impossible; \( j_{h'} \in D_g \setminus R_p \)). Thus \( h \leq M = \max \{ m \mid p(i_m) < j_{h'} \} \). This yields the contradiction

\[
a = i_h + n(1 + h) \leq i_M + n(1 + M) \leq j_{h'} + i_M + n(1 + M) = b
\]

Next an edit sequence \( s \) taking \( u \) to \( v \) will be constructed. Let

\[
E = \{ b \to a \mid b \in D_u \setminus A \}
\]

\[
C = \{ a \to v(a) \mid a \in A \}
\]

\[
I = \{ b \to v(b) \mid b \in B \}
\]

Let \( s' \) be the sequence of elements in \( E \), let \( s'' \) be the sequence of elements in \( C \), and let \( s''' \) be the sequence of elements in \( I \). Define \( s \) as \( s'''s''s' \). Note that \( s'(u) \) is defined and is simply the restriction of \( u \) to \( A \). Therefore, \( s''s'(u) \) is defined and is simply the restriction of \( v \) to \( A \). Since \( A \cup B = D_v \) and \( A \) and \( B \) are disjoint, \( s'''s''s'(u) \) is defined and is \( v \).

The proof is completed by showing that \( \gamma(s) = \gamma(t) \). By theorem 4 and the definition of the cost of an edit sequence,

\[
\gamma(s) = \gamma(s''', s''s'(u)) + \gamma(s'', s'(u)) + \gamma(s', u)
\]

\[
= |I| \gamma_s + \gamma(s'', s'(u)) + |E| \gamma_d
\]

Note that

\[
|E| = |D_u \setminus A| = |D_u| - |A| = |D_u| - |D_p| = |D_f| - |D_p| = |D_f \setminus D_p|
\]

\[
|I| = |B| = |D_g \setminus R_p|
\]

It follows that \( \gamma(s) = \gamma(t) \) provided

\[
\gamma(s'', s'(u)) = \sum_{(i, j) \in p} \gamma(i \to g(f(j), f))
\]  

(3)

Both sides of equation 3 contain \( |C| = |A| = |D_p| \) terms, but some could be zero because change operators may be trivial. The right hand side can be rewritten as

\[
\sum_{i_h \in D_p} \gamma(i_h \to g(p(i_h)), f)
\]
A term (corresponding to $i_h \in D_p$) is trivial exactly when $g(p(i_h)) = f_h$. Since $v(a) = g \circ \varphi(a)$, the left hand side of equation 3 can be rewritten as

$$
\sum_{i_h \in D_p} \gamma(i_h + n(1 + h) \rightarrow g(p(i_h)), s'(u))
$$

A term (corresponding to $i_h \in D_p$) is trivial exactly when

$$
g(p(i_h)) = s'(u)(i_h + n(1 + h)) = u(i_h + n(1 + h)) = f_h
$$

□

Let $t = (p, f, g)$ and $t' = (p', f, h)$ be two traces. Their composition $t' \circ t$ is the trace $(p' \circ p, f, h)$ from $f$ to $h$ where the composition $p' \circ p$ of partial functions is defined as

$$
p' \circ p = \{(i, k) \mid \exists j. (i, j) \in p \text{ and } (j, k) \in p'\}
$$

Note that the composition $t' \circ t$ is defined only when the third component of $t$ is equal to the second component of $t'$. In this case they are said to be composeable.

**Lemma 12** Given composeable traces $t$ and $t'$, $\gamma(t' \circ t) \leq \gamma(t) + \gamma(t')$.

Proof: Let $t = (p, f, g)$ and $t' = (p', g, h)$. Note that

$$
|D_f \setminus D_p| + |D_g \setminus D_{p'}| \geq |D_f| - |D_p| + |R_p \setminus D_{p'}|
$$

$$
= |D_f| - (|R_p| - |R_p \setminus D_{p'}|)
$$

$$
= |D_f| - |R_p \cap D_{p'}|
$$

$$
= |D_f \setminus D_{p' \circ p}|
$$

$$
|D_g \setminus R_p| + |D_h \setminus R_{p'}| \geq |D_{p'} \setminus R_p| + |D_{p} - D_{p'}|
$$

$$
= |D_{p'}| - (|R_p| - |R_p \setminus D_{p'}|)
$$

$$
= |D_{p'}| - |D_{p'} \cap R_p|
$$

$$
= |D_{p'}| - |D_{p' \circ p}|,
$$

$$
= |D_{p'} \setminus R_{p' \circ p}|
$$

Therefore

$$
\gamma(t) + \gamma(t') = (|D_f \setminus D_p| + |D_g \setminus D_{p'}|) \cdot \gamma_d + (|D_g \setminus R_p| + |D_h \setminus R_{p'}|) \cdot \gamma_i
$$

$$
+ \sum_{(i, j) \in p} \gamma(i \rightarrow g(j), f) + \sum_{(j, k) \in p'} \gamma(j \rightarrow h(k), g)
$$

$$
\geq |D_f \setminus D_{p' \circ p}| \cdot \gamma_d + |D_h \setminus R_{p' \circ p}| \cdot \gamma_i
$$

$$
+ \sum_{(i, j) \in p} \gamma(i \rightarrow g(j), f) + \sum_{(j, k) \in p'} \gamma(j \rightarrow h(k), g)
$$
The proof is completed by showing
\[ \sum_{(i,k) \in p'} \gamma(i \to h(k), f) \leq \sum_{(i,j) \in p} \gamma(i \to g(j), f) + \sum_{(j,k) \in p'} \gamma(j \to h(k), g) \]

In the expression above, an edit operation corresponding to \((i,j) \in p\) is trivial exactly when \(f(i) = g(j)\), and an edit operation corresponding to \((j,k) \in p'\) is trivial exactly when \(g(j) = h(k)\). When both are trivial, \(f(i) = g(j) = h(k)\) and the edit operation corresponding to \((i,k) \in p' \circ p\) is trivial. Consequently, to each nonzero term (i.e., nontrivial edit operation) in the first summation, there is a corresponding nonzero term in the second or third summation.
\[ \square \]

**Theorem 13** Let \(s\) be an edit sequence taking \(f\) to \(g\). There exists a trace \(t\) taking \(f\) to \(g\) such that \(\gamma(t) \leq \gamma(s)\).

Proof: Induct on the length of \(s\). Base case: \(s = \varepsilon\). Note that \(D_f = D_g\) since \(g = s(f) = f\). Let \(id : D_f \to D_g\) be the identity function. Let \(t = (id, f, g)\) and note that \(D_f = D_{id} = D_g\). Therefore
\[ \gamma(t) = \sum_{(i,j) \in id} \gamma(i \to f(j), f) \]

Every term in this sum is zero, since \((i,j) \in id \implies i = j \implies f(i) = f(j)\).

Inductive step: Let \(s = e_0 \ldots e_k\), and let \(h = e_1 \ldots e_k (f)\). By the inductive hypothesis, there exists a trace \(t'\) taking \(f\) to \(h\) such that \(\gamma(t') \leq \gamma(e_1 \ldots e_k)\).

Since \(s(f) = g\), it follows that \(e_0\) takes \(f\) to \(g\). The proof is completed by exhibiting a trace \(t''\) taking \(h\) to \(g\) such that \(\gamma(t'') = \gamma(e_0)\). Then \(t = t'' \circ t'\) takes \(f\) to \(g\) and by lemmas 12 and 4,
\[ \gamma(t) \leq \gamma(t'') + \gamma(t') \leq \gamma(e_0) + \gamma(e_1 \ldots e_k) = \gamma(s) \]

There are three cases to consider, depending on the type of \(e_0\).

Case 1: \(e_0 = m \to g(m)\). Note that \(D_h = D_g\) since \(m \to g(m) (h) = g\). Let \(id : D_h \to D_g\) be the identity function. Let \(t'' = (id, h, g)\) and note (as in the base case) that
\[ \gamma(t'') = \sum_{i \in D_h} \gamma(i \to g(i), h) \]

Every term in this sum is zero, except possibly for \(\gamma(m \to g(m), h)\), since \(i \neq m \implies g(i) = h(i)\).
Case 2: $e_0 = m \rightarrow g(m)$. Note that $D_g = \{ m \} \cup D_h$ since $m \rightarrow g(m) (h) = g$.
Let $id : D_h \rightarrow D_g$ be the identity function. Let $t'' = (id, h, g)$ and note that $D_g \setminus R_{id} = \{ m \}$. Therefore
\[
\gamma(t'') = \sum_{i \in D_h} \gamma(i \rightarrow g(i), h)
\]
Every term in the summation over $D_h$ is zero, since $i \in D_h \implies g(i) = h(i)$.

Case 3: $e_0 = m \rightarrow m$. Note that $D_h = \{ m \} \cup D_g$ since $m \rightarrow (h) = g$. Let $id^{-1} : D_g \rightarrow D_h$ be the identity function (observe that $id$ is a partial function from $D_h$ to $D_g$). Let $t'' = (id, h, g)$ and note that $D_h \setminus D_{id} = \{ m \}$. Therefore
\[
\gamma(t'') = \sum_{i \in D_g} \gamma(i \rightarrow g(i), h)
\]
Every term in the summation over $D_h$ is zero, since $i \in D_g \implies g(i) = h(i)$. 
\textsquare

An edit sequence $s$ is said to take $[f]$ to $[g]$ if there exists $u \in [f]$ and $v \in [g]$ such that $s(u) = v$. A trace $t$ is said to take $[f]$ to $[g]$ if its second component is equivalent to $f$ and its third component is equivalent to $g$.

To refer to the cost of an edit sequence $s$ taking $[f]$ to $[g]$ is to refer to
\[
\gamma(s, [f], [g]) = \min \{ \gamma(s, u) \mid u \in [f], s(u) \in [g] \}
\]

An edit sequence $s$ is called a minimal cost edit sequence taking $[f]$ to $[g]$ if it takes $[f]$ to $[g]$ and among all such edit sequences its cost (as given by the expression above) is minimal.

**Theorem 14** If $s$ is a minimal cost edit sequence taking $[f]$ to $[g]$, and $t$ is a minimal cost trace taking $[f]$ to $[g]$, then $\gamma(s, [f], [g]) = \gamma(t)$.

Proof: By assumption, there exist $u \in [f]$ and $v \in [g]$ such that $s(u) = v$. Moreover, $\gamma(s, u)$ is minimal in the sense that it cannot decrease by changing $s$ or $u$ subject to the constraints that $u \in [f]$ and $s(u) \in [g]$. By theorem 13, there exists a trace $t'$ from $u$ to $v$ such that $\gamma(t') \leq \gamma(s, u)$. By theorem 11, there exists an edit sequence $s'$ taking $[u] = [f]$ to $[v] = [g]$ with cost no greater than $\gamma(t')$. That cost must in fact be $\gamma(s, u)$, since otherwise the minimality of $\gamma(s, u)$ would be contradicted. Therefore $\gamma(t') = \gamma(s, u)$. The proof is completed by showing $\gamma(t') \leq \gamma(t)$ ($\gamma(t) = \gamma(t') = \gamma(s, u)$ would then follow by minimality of $\gamma(t)$).

Let $t = (t_1, t_2, t_3)$. By theorem 11, there exists an edit sequence $s''$ taking $[t_2] = [f]$ to $[t_3] = [g]$ with cost no greater than $\gamma(t)$. Its cost contradicts
the minimality of $\gamma(s, u)$ if $\gamma(t) < \gamma(t')$.

\[\square\]

Extend the concept of edit distance to equivalence classes by

$$\delta([f], [g]) = \min\{\delta(u, v) \mid u \in [f], v \in [g]\}$$

Since $\delta(u, v)$ is the minimum with respect to $s$ of $\gamma(s, u)$ subject to $s(u) = v$, it follows that $\delta([f], [g])$ is the cost of a minimal cost edit sequence taking $[f]$ to $[g]$. By theorem 14, that coincides with the cost of a minimal cost trace taking $[f]$ to $[g]$.

**Lemma 15** Let $t = (t_1, t_2, t_3)$ be a trace, and let $t'$ be a trace taking $[t_2]$ to $[t_3]$. There exists a partial function $t^*_t : D_{t_2} \to D_{t_3}$ such that $t^* = (t^*_t, t_2, t_3)$ is a trace and $\gamma(t^*) = \gamma(t')$.

Proof: Let $t' = (t'_1, t'_2, t'_3)$. Since $t'_2 \equiv t_2$ and $t'_3 \equiv t_3$, by lemma 10 there exist one-to-one and onto order-preserving functions $\varphi_2 : D_{t_2} \to D_{t'_2}$ and $\varphi_3 : D_{t'_3} \to D_{t_3}$ such that $t_2 = t'_2 \circ \varphi_2$ and $t'_3 = t_3 \circ \varphi_3$. Let $t'_t = \varphi_3 \circ t'_2 \circ \varphi_2$, and note that $t'_t$ is an increasing partial function from $D_{t_1}$ to $D_{t_3}$. Hence $t^* = (t^*_t, t_2, t_3)$ is a trace. Because $\varphi_2$ and $\varphi_3$ are isomorphisms,

$$|D_{t_2} \setminus D_{t'_2}| = |D_{t_2} - |D_{t_2} \circ \varphi_2| = |D_{t'_2} - |D_{t'_2} \circ \varphi_2| = |D_{t'_2} \setminus D_{t'_2}|$$

$$|D_{t_3} \setminus R_{t'_1}| = |D_{t_3} - |R_{t_3} \circ \varphi_3| = |D_{t_3} - |R_{t_3} \circ \varphi_3| = |D_{t_3} \setminus R_{t_3}|$$

It follows that $\gamma(t^*) = \gamma(t')$ provided the following equality holds

$$\sum_{(u, v) \in \varphi_2 \circ t'_2 \circ \varphi_2} \gamma(u \mapsto t_3(v), t_2) = \sum_{(i, j) \in t'_t} \gamma(i \mapsto t'_3(j), t'_2)$$

Replacing $t_3$ with $t'_3 \circ \varphi_3^{-1}$, replacing $t_2$ with $t'_2 \circ \varphi_2$ and making the change of variables $i = \varphi_2(u)$, $v = \varphi_3(j)$ puts the left hand side of the equality into the form

$$\sum_{(i, j) \in t'_t} \gamma(\varphi_2^{-1}(i) \mapsto t'_3 \circ \varphi_3^{-1}(\varphi_3(j)), t'_2 \circ \varphi_2)$$

A term corresponding to $(i, j)$ (in the left hand side of the equality) is therefore zero exactly when

$$t'_3(j) = t'_2 \circ \varphi_2(\varphi_2^{-1}(i)) = t'_2(i)$$

A term corresponding to $(i, j)$ in the right hand side of the equality is zero exactly when

$$t'_2(j) = t'_2(i)$$

\[\square\]
**Theorem 16** Edit distance is a metric on equivalence classes of \( \equiv \) if and only if \( \gamma_i = \gamma_d \). Moreover, the following are equal

1. \( \delta([f], [g]) \)

2. The cost of a minimal cost edit sequence taking \([f]\) to \([g]\).

3. The cost of a minimal cost trace taking \([f]\) to \([g]\).

4. \( \min\{\gamma((p, f, g)) \mid p : D_f \to D_g \text{ is an increasing partial function} \} \)

Proof: The equality of the first three quantities listed was already noted in the discussion preceding lemma 15. Note that \((p, f, g)\) (where \(p : D_f \to D_g\) is an increasing partial function) is a trace taking \([f]\) to \([g]\). Hence the fourth quantity listed is at least \( \delta([f], [g]) \). Let \( t' \) be a minimal cost trace taking \([f]\) to \([g]\). By lemma 15, there exists an increasing partial function \( p : D_f \to D_g \) such that \( \gamma((p, f, g)) = \gamma(t') \). Therefore all four quantities listed above are equal.

Assume edit distance is a metric on equivalence classes of \( \equiv \). Then it is symmetric. The same argument as given in the proof of theorem 9 shows

\[
\delta([\emptyset], [(0, a)]) = \delta([(0, a)], [\emptyset]) \implies \gamma_i = \gamma_d
\]

Assume \( \gamma_i = \gamma_d \). Since \( \delta(f, g) \) is nonnegative, so too is \( \delta([f], [g]) \). Since \( \delta(f, g) \) is symmetric, so too is \( \delta([f], [g]) \). If \( \delta([f], [g]) = 0 \), then there exist \( u \in [f] \) and \( v \in [g] \) such that \( \delta(u, v) = 0 \). Hence \( u = v \) and \([f] = [g]\).

Moreover, \( \delta([f], [f]) \leq \delta(f, f) = 0 \). It remains to establish the triangle inequality.

By what has already been established, let \( t = (p, f, h) \) be a trace such that \( \delta([f], [h]) = \gamma(t) \). Similarly, let \( t' = (g', h, g) \) be a trace such that \( \delta([h], [g]) = \gamma(t') \). Note that \( t' \circ t \) is a trace taking \([f]\) to \([g]\). By lemma 12,

\[
\delta([f], [g]) \leq \gamma(t' \circ t) \leq \gamma(t) + \gamma(t') = \delta([f], [h]) + \delta([h], [g])
\]

\(\Box\)

Trace \( t \) is said to be **minimal** if \( \gamma(t) = \delta([h_2], [t_3]) \). Note that it makes sense to speak of a minimal trace from \( f \) to \( g \); that refers to a trace \((p, f, g)\) for which \( \gamma((p, f, g)) = \delta([f], [g]) \). According to theorem 16, such a trace exists.

Traces \( t = (t_1, t_2, t_3) \) and \( t' = (t'_1, t'_2, t'_3) \) are said to be **compatible** provided that \( D_{t_2} \cap D_{t'_2} = \emptyset = D_{t_3} \cap D_{t'_3} \), and for all \((i, j) \in t_1 \) and all \((i', j') \in t'_1 \)

\[
i < i' \implies j < j' \quad \text{and} \quad i' < i \implies j' < j
\]
If \( t \) and \( t' \) are compatible, then \( t \oplus t' \) is defined as
\[
t \oplus t' = (t_1 \cup t'_1, t_2 \cup t'_2, t_3 \cup t'_3)
\]
If \( t \) and \( t' \) are not compatible, then \( t \oplus t' \) is undefined.

**Lemma 17** If \( t \oplus t' \) is defined, then it is is a trace and \( \gamma(t \oplus t') = \gamma(t) + \gamma(t') \).

Proof: Let \( t = (t_1, t_2, t_3) \) and \( t' = (t'_1, t'_2, t'_3) \) be compatible traces. Then \( \emptyset = D_{t_2} \cap D_{t'_2} = D_{t_3} \cap D_{t'_3} \). Since \( t_2 \) and \( t'_2 \) have disjoint domains, \( t_2 \cup t'_2 \) is a function and
\[
D_{t_2 \cup t'_2} = D_{t_2} \cup D_{t'_2}
\]
Likewise, \( t_3 \cup t'_3 \) is a function and
\[
D_{t_3 \cup t'_3} = D_{t_3} \cup D_{t'_3}
\]
Likewise, \( t_1 \cup t'_1 \) is a function which is partitioned by \( t_1 \) and \( t'_1 \). Hence \( t_1 \cup t'_1 \) is a partial function from \( D_{t_1 \cup t'_1} \) to \( D_{t_3 \cup t'_3} \). Moreover, \( t_1 \cup t'_1 \) is increasing since for all \((i, j) \in t_1 \) and all \((i', j') \in t'_1 \)
\[
i < i' \implies j < j' \quad \text{and} \quad i' < i \implies j' < j
\]
If \((i, j)\) and \((i', j')\) are both in either \( t_1 \) or \( t'_1 \), the above implications hold because \( t_1 \) and \( t'_1 \) are increasing. Therefore, \( t \oplus t' \) is a trace. Note that, because of the disjoint unions involved,
\[
|D_{t_2 \cup t'_2} \setminus D_{t_1 \cup t'_1}| = |D_{t_2}| + |D_{t'_2}| - |D_{t_1}| - |D_{t'_1}|
= |D_{t_2}| + |D_{t'_2}| - |D_{t_1}| - |D_{t'_1}|
= |D_{t_2} \setminus D_{t_1}| + |D_{t'_2} \setminus D_{t'_1}|

|D_{t_3 \cup t'_3} \setminus R_{t_1 \cup t'_1}| = |D_{t_3}| + |D_{t'_3}| - |R_{t_1}| - |R_{t'_1}|
= |D_{t_3}| + |D_{t'_3}| - |R_{t_1}| - |R_{t'_1}|
= |D_{t_3} \setminus R_{t_1}| + |D_{t'_3} \setminus R_{t'_1}|

\[
\sum_{(i, j) \in t_1 \cup t'_1} \gamma(i \rightarrow (t_3 \cup t'_3)(j), t_2 \cup t'_2) = \sum_{(i, j) \in t_1} \gamma(i \rightarrow t_3(j), t_2) + \sum_{(i', j') \in t'_1} \gamma(i' \rightarrow t'_3(j'), t'_2)
\]

Therefore, \( \gamma(t \oplus t') = \gamma(t) + \gamma(t') \).
\[\square\]

Trace \( t = (t_1, t_2, t_3) \) is said to **precede** trace \( t' = (t'_1, t'_2, t'_3) \), denoted \( t \prec t' \), provided
\[
\max \{i \mid i \in D_{t_2}\} < \min \{i \mid i \in D_{t'_2}\}
\]
\[
\max \{i \mid i \in D_{t_3}\} < \min \{i \mid i \in D_{t'_3}\}
\]
where \( \max \emptyset = -\infty \) and \( \min \emptyset = +\infty \).

**Theorem 18** If \( t = (t_1, t_2, t_3) < t' = (t'_1, t'_2, t'_3) \), then \( t \oplus t' \) is a trace. If \( t \oplus t' \) is minimal, then so are \( t \) and \( t' \).

Proof: By lemma 17, \( t \oplus t' \) is a trace provided that and \( t' \) are compatible. Since \( t \) precedes \( t' \), it follows that \( D_{t_2} \cap D_{t'_2} = \emptyset = D_{t_3} \cap D_{t'_3} \). Moreover, if \((i, j) \in t_1 \) and \((i', j') \in t'_1 \), then \( i < i' \) and \( j < j' \). Hence \( t \) and \( t' \) are compatible. Note that the compatibility of traces \( t \) and \( t' \) is not influenced by either \( t_1 \) or \( t'_1 \), because the compatibility follows from \( t < t' \) which is defined independent of \( t_1 \) and \( t'_1 \) (whether \( t \) precedes \( t' \) depends only on \( D_{t_2}, D_{t_3}, D_{t'_2}, D_{t'_3} \)). Therefore (by lemma 17)

\[
\gamma(t \oplus t') = \gamma(t) + \gamma(t')
\]

and this equality remains valid when \( t_1 \) and \( t'_1 \) are treated as parameters and are allowed to change. Suppose \( t \oplus t' \) is minimal. Then the left hand side of the equality is \( \delta([t_2 \cup t'_2], [t_3 \cup t'_3]) \). By theorem 16, it cannot decrease by changing \( t_1 \cup t'_1 \). However, if either \( t \) or \( t' \) were not minimal, then (by theorem 16) the right hand side of the equality could decrease by changing \( t_1 \) or \( t'_1 \).

\( \square \)

**Lemma 19** Let \( t = (t_1, t_2, t_3) \) be a trace. Let \( t_2 = \{(i_0, f_0), \ldots, (i_k, f_k)\} \) where \( i_0 < \cdots < i_k \), and let \( t_3 = \{(j_0, g_0), \ldots, (j_l, g_l)\} \) where \( j_0 < \cdots < j_l \). If \( t_2 \) and \( t_3 \) are nonempty, then \( t \) can be expressed as \( t = t'' \oplus t' \) where one of the following cases hold.

1. \( t' = \{(i_k, j_k), (i_k, f_k), (j_k, g_k)\} \)
2. \( t' = (\emptyset, (i_k, f_k), \emptyset) \)
3. \( t' = (\emptyset, \emptyset, (j_k, g_k)) \)

Moreover, if \( t \) is minimal, then so is \( t'' \).

Proof: Let \( t' = (t'_1, t'_2, t'_3) \). The three cases correspond to a case decomposition based on \( t_1 \). The first case is \((i_k, j_k) \in t_1 \), which can be described by saying both \( i_k \in D_{t_1} \) and \( j_k \in R_{t_1} \). The second case is \( i_k \notin D_{t_1} \) and \( j_k \in R_{t_1} \). The third case is \( j_k \notin R_{t_1} \). In each case \( t'' = (t''_1, t''_2, t''_3) \) must (by the definition of \( \oplus \)) be defined by

\[
\begin{align*}
t''_1 &= t_1 \setminus t'_1 \\
t''_2 &= t_2 \setminus t'_2 \\
t''_3 &= t_3 \setminus t'_3
\end{align*}
\]
In every case, \( t' \) is clearly a trace. Moreover, \( t'' \oplus t' \) is a trace (via theorem 18), assuming that \( t'' \) is a trace, since \( t'' \prec t' \).

In case 1, \( t''_1 \) is a partial function from \( D_{t_3 \setminus \{i_k\}} = D_{t_3 \setminus \{i_k\}} \) to \( D_{t_3 \setminus \{i_k\}} = D_{t_3 \setminus \{i_k\}} \). Thus \( t'' \) is a trace.

In case 2, \( t''_1 = t_1 \) is a partial function from \( D_{t_3 \setminus \{i_k\}} = D_{t_3 \setminus \{i_k\}} \) to \( D_{t_3 \setminus \{i_k\}} \), because \( i_k \notin D_{t_1} \). Thus \( t'' \) is a trace.

In case 3, \( t''_1 = t_1 \) is a partial function from \( D_{t_3} \) to \( D_{t_3 \setminus \{i_k\}} = D_{t_3 \setminus \{i_k\}} \), because \( j_k \notin R_{t_3} \). Thus \( t'' \) is a trace.

If \( t \) is minimal, then by theorem 18 so is \( t'' \).

\[ \square \]

4 The Normal Distance Matrix

Define the distance between normal representations \( \tilde{f} \) and \( \tilde{g} \) as

\[
d(\tilde{f}, \tilde{g}) = \delta([f], [g])
\]

Note that distance is well-defined since \( \tilde{f} = \tilde{h} \iff [f] = [h] \). By theorem 16, distance is a metric on normal representations if and only if \( \gamma_i = \gamma_0 \).

Let \( s = e_0 \ldots e_k \) be an edit sequence taking \( u \) to \( v \). Normal representation \( \bar{u} \) is regarded as being transformed to \( \bar{v} \) through the following sequence \( \bar{s} \) of normal representations

\[
\bar{s} = \Psi(u)\psi(e_k(u))\Psi(e_{k-1}e_k(u))\ldots\Psi(e_0\ldots e_k(u))
\]

Each step in the sequence (from one element to the next) corresponds to one of three types of operations on normal representations. Let \( \bar{w} = w_0 \ldots w_n \).

If \( e_i \) is a delete operation, then

\[
w_0 \ldots w_n \mapsto \Psi(e_i(w)) = w'_0 \ldots w'_{n-1}
\]

where there exists \( 0 \leq l \leq n \) such that

\[
w'_j = \begin{cases} w_j & \text{if} \ j < l \\
w_{j+1} & \text{if} \ j > l
\end{cases}
\]

In other words, the \( l \)th element of \( \bar{w} \) has been removed. If \( e_i = m \rightarrow b \) is a change operation, then

\[
w_0 \ldots w_n \mapsto \Psi(e_i(w)) = w'_0 \ldots w'_n
\]

18
where there exists $0 \leq l \leq n$ such that

$$w'_j = \begin{cases} w_j & \text{if } j \neq l \\ b & \text{if } j = l \end{cases}$$

In other words, the $l$th element of $\bar{w}$ has been changed; this is called a trivial change when $b = w_l$. If $e_i = m \rightarrow b$ is an insert operation, then

$$w_0 \ldots w_n \mapsto \Psi(e_i(w)) = w_0' \ldots w_n'$$

where there exists $0 \leq l \leq n + 1$ such that

$$w'_j = \begin{cases} w_j & \text{if } j < l \\ b & \text{if } j = l \\ w_{j-1} & \text{if } j > l \end{cases}$$

In other words, $b$ has been inserted into $\bar{w}$ at position $l$.

To streamline exposition, refer to the three types of operations (on normal representations described above) as delete, change, and insert operations. Let them have respective costs $\gamma_d$, $\gamma_c$, and $\gamma_i$, except that the cost of a trivial change is zero. To distinguish these operators (which act on normal representations) from previously discussed operators, they are called normal operators. The sum of the costs of the normal operators corresponding to the steps (from one element to the next) in the sequence $\bar{s}$ is therefore $\gamma(s)$.

Given any sequence $r$ of normal representations

$$r = \bar{h}_0 \bar{h}_1 \ldots \bar{h}_n$$

such that $\bar{h}_{i+1}$ is the result of some normal operator $o_i$ applied to $\bar{h}_i$, define its cost $\gamma(r)$ as the sum (over $0 \leq i < n$) of the costs of the operators $o_i$.

Such a sequence is referred to as a normal sequence, and is described as being from $\bar{h}_0$ to $\bar{h}_n$. By the discussion above, if $s = e_0 \ldots e_k$ is an edit sequence taking $u$ to $v$, then the sequence

$$\bar{s} = \Psi(u)\Psi(e_k(u)) \ldots \Psi(e_0 \ldots e_k(u))$$

is a normal sequence taking $\bar{u}$ to $\bar{v}$. Moreover, $\gamma(\bar{s}) = \gamma(s)$.

A minimum normal sequence from $\bar{f}$ to $\bar{g}$ is a minimal cost normal sequence from $\bar{f}$ to $\bar{g}$. Define $m(\bar{f}, \bar{g})$ as the cost of a minimum normal sequence from $\bar{f}$ to $\bar{g}$. Hence $m(\bar{f}, \bar{g}) \leq \gamma(\bar{s}) = \gamma(s)$ where $s$ is a minimal cost edit sequence taking $[f]$ to $[g]$. It follows (via theorem 16) that

$$m(\bar{f}, \bar{g}) \leq d(\bar{f}, \bar{g})$$

There may be question as to whether $m(\bar{f}, \bar{g}) = d(\bar{f}, \bar{g})$, because it has not yet been established that every normal sequence $r$ can be expressed as $\bar{s}$ for some edit sequence $s$. The following lemma shows that to be the case, and therefore $m(\bar{f}, \bar{g})$ and $d(\bar{f}, \bar{g})$ coincide.
Lemma 20  Given nonempty normal sequence \( r \), there exists \( u \) and \( v \) and an edit sequence \( s \) taking \( u \) to \( v \) such that \( r = \tilde{s} \).

Proof: To facilitate induction on the length of \( r \), a stronger result will be proved; in addition, \( u \) may be chosen such that the distance between consecutive elements of \( D_u \) is arbitrarily large.

Base case: \( r = \overline{h} \) where \( h = \{(i_0, f_0), \ldots, (i_t, f_t)\} \). Let \( n \in \mathbb{Z}^+ \) be arbitrary, and let \( u = \{(i_0n, f_0), \ldots, (i_tn, f_t)\} \). Let \( s = \varepsilon \) so that \( \tilde{s} = \overline{a} = \overline{h} = r \). Moreover, the distance between consecutive elements of \( D_u \) is at least \( n \).

Inductive step: \( r = \overline{h}_0 \ldots \overline{h}_k \) where \( \overline{h}_0 = a_0 \ldots a_q \). Let \( o \) be the normal operator taking \( \overline{h}_0 \) to \( \overline{h}_1 \), and let \( p \) be the location at which a change, insertion, or deletion takes place in \( \overline{h}_0 \). Let \( n \in \mathbb{Z}^+ \) be arbitrary, and let \( s \) be an edit sequence taking \( \overline{h}_1 \) to \( \overline{h}_k \) such that \( \tilde{s} = \overline{h}_1 \ldots \overline{h}_k \). Let \( \overline{h}_1 = \{(i_0, f_0), \ldots, (i_t, f_t)\} \) where \( i_0 < \cdots < i_t \) and the distance between consecutive elements of \( D_{h_1} \) is greater than \( 2n \). The proof is completed by showing there exists an edit operation \( e \) taking \( u \) to \( h_1 \) where \( u \) may be chosen such that \( \overline{a} = \overline{h}_0 \) and the distance between consecutive elements of \( D_u \) is at least \( n \). The required edit sequence is then \( se \). There are three cases to consider, depending on the type of \( o \).

Case 1: \( o \) is a change operator. Then \( \overline{h}_0 = \overline{h}_1 \) except perhaps at position \( p \). Let \( u = i_{p} \rightarrow a_{p} (h_1) \) and let \( e = i_{p} \rightarrow f_{p} \). Then \( \overline{a} = \overline{h}_0 \) and \( e(u) = h_1 \) as required. Moreover, the distance between consecutive elements of \( D_u = D_{h_1} \) is at least \( n \).

Case 2: \( o \) is an insert operator. Then the element inserted by \( o \) is \( f_p \) and \( h_0 = f_0 \ldots f_{p-1} f_{p+1} \ldots f_q \). Let \( u = i_{p} \rightarrow (h_1) \) and let \( e = i_{p} \rightarrow f_{p} \). Then \( \overline{a} = \overline{h}_0 \) and \( e(u) = h_1 \) as required. Moreover, the distance between consecutive elements of \( D_u = D_{h_1} \setminus \{i_p\} \) is at least \( n \).

Case 3: \( o \) is a delete operator. Then \( h_1 = a_0 \ldots a_{p-1} a_{p+1} \ldots a_q \). Let \( i \) be \([i_{p-1} + i_p]/2\). Let \( u = i \rightarrow a_{p} (h_1) \) and let \( e = i \rightarrow \). Then \( \overline{a} = \overline{h}_0 \) and \( e(u) = h_1 \) as required. Moreover, the distance between consecutive elements of \( D_u = D_{h_1} \cup \{i_p\} \) is at least \( n \).

\[ \square \]

Theorem 21  Distance \( d(\overline{f}, \overline{g}) \) defined as the cost of a minimal trace taking \( f \) to \( g \) is a metric on normal representations if and only if \( \gamma_k = \gamma_d \). Moreover, \( d(\overline{f}, \overline{g}) \) is equal to the cost of a minimal normal sequence from \( f \) to \( g \).

Proof: Theorem 16 established the claims regarding distance being a metric. Lemma 20 and the discussion preceding it complete the proof.

\[ \square \]
Given string \( f = \{ (i_0, f_0), \ldots, (i_k, f_k) \} \) where \( i_0 < \cdots < i_k \), define \( \sigma_j(f) \) for \( 0 < j \leq |f| \) to be the normal representation of \( \{ (i_0, f_0), \ldots, (i_{j-1}, f_{j-1}) \} \),

\[
\sigma_j(f) = f_0 \cdots f_{j-1}
\]

Let \( \sigma_0(f) \) be the empty sequence \( \varepsilon \). Note that if \( f \equiv h \) then \( \sigma_j(f) = \sigma_j(h) \), so \( f \) may as well be normalized. Moreover, \( \sigma_{|f|}(f) \) is the normal representation of \( f \).

Given strings \( f \) and \( g \), their normal distance matrix is the \( 1 + |f| \times 1 + |g| \) matrix \( D \) with \( i,j \) entry (for \( 0 \leq i \leq |f| \) and \( 0 \leq j \leq |g| \))

\[
D_{i,j} = d(\sigma_i(f), \sigma_j(g))
\]

In particular, \( D_{|f|,|g|} \) is the distance between the normal representations of \( f \) and \( g \).

The notation [expression] is used in the following theorem to simplify exposition. It is defined as

\[
[expression] = \begin{cases} 
1 & \text{if expression is true} \\
0 & \text{otherwise}
\end{cases}
\]

**Theorem 22** Let \( f \) and \( g \) be nonempty normalized strings. For \( 0 < u \leq |f| \) and \( 0 < v \leq |g| \), their normal distance matrix \( D \) satisfies

\[
\begin{align*}
D_{0,0} &= 0 \\
D_{0,v} &= v \gamma_i \\
D_{u,0} &= u \gamma_d \\
D_{u,v} &= \min\{\gamma_c[f(u-1) \neq g(v-1)] + D_{u-1,v-1}, \gamma_d + D_{u-1,v}, \gamma_i + D_{u,v-1}\}
\end{align*}
\]

Proof: Let \( \bar{f} = f_0 \cdots f_k \) and \( \bar{g} = g_0 \cdots g_k \). Using normal operators on normal representations (which is justified by theorem 21), it is clear that

\[
\begin{align*}
D_{0,0} &= d(\varepsilon, \varepsilon) = 0 \\
D_{0,v} &= d(\varepsilon, g_0 \cdots g_{v-1}) = v \gamma_i \\
D_{u,0} &= d(f_0 \cdots f_{u-1}, \varepsilon) = u \gamma_d
\end{align*}
\]

Note that \( D_{u,v} = d(f_0 \cdots f_{u-1}, g_0 \cdots g_{v-1}) = \gamma(t) \) where \( t = (t_1, t_2, t_3) \) is a minimal trace taking \( \Phi(f_0 \cdots f_{u-1}) \) to \( \Phi(g_0 \cdots g_{v-1}) \). Appealing to lemmas 17 and 19, \( D_{u,v} = \gamma(t'') + \gamma(t') \) where \( t = t'' \oplus t' \) and one of the following cases holds.

Case 1: If \( t' = \{(i_{u-1}, f_{u-1})\}, \{(i_{u-1}, f_{u-1})\}, \{(j_{v-1}, g_{v-1})\} \), then

\[
\gamma(t') = \gamma(i_{u-1} \rightarrow g_{v-1}, \{(i_{u-1}, f_{u-1})\}) = \gamma_c[f_{u-1} \neq g_{v-1}]
\]

21
Moreover, $t''$ is a minimal trace taking $\Phi(f_0 \ldots f_{u-2})$ to $\Phi(g_0 \ldots g_{v-2})$. Thus $\gamma(t'') = D_{u-1,v-1}$.

Case 2: If $t' = (\emptyset, \{(i_{u-1}, f_{u-1})\}, \emptyset)$, then $\gamma(t') = \gamma_d$ and $t''$ is a minimal trace taking $\Phi(f_0 \ldots f_{u-2})$ to $\Phi(g_0 \ldots g_{v-1})$. Thus $\gamma(t'') = D_{u-1,v}$.

Case 3: If $t' = (\emptyset, \emptyset, \{(j_{v-1}, g_{v-1})\})$, then $\gamma(t') = \gamma_i$ and $t''$ is a minimal trace taking $\Phi(f_0 \ldots f_{u-1})$ to $\Phi(g_0 \ldots g_{v-2})$. Thus $\gamma(t'') = D_{u,v-1}$.

It follows that $D_{u,v}$ is equal to some element of the set

$$\{\gamma_c[f(u-1) \neq g(v-1)], D_{u-1,v-1}, \gamma_d, D_{u-1,v}, \gamma_i, D_{u,v-1}\}$$

If each element in this set is the cost of some sequence of normal operators taking $f_0 \ldots f_{u-1}$ to $g_0 \ldots g_{v-1}$, then the proof is complete by the minimality of $D_{u,v}$.

The first element in the set is the cost of changing $f_{u-1}$ to $g_{v-1}$ by a normal change operator followed by the cost of $s$ where $s$ is a minimal cost edit sequence from $[\Phi(f_0 \ldots f_{u-2})]$ to $[\Phi(g_0 \ldots g_{u-2})]$.

The second element in the set is the cost of deleting $f_{u-1}$ by a normal delete operator followed by the cost of $s$ where $s$ is a minimal cost edit sequence from $[\Phi(f_0 \ldots f_{u-2})]$ to $[\Phi(g_0 \ldots g_{u-1})]$.

The third element in the set is the cost of $s$ where $s$ is a minimal cost edit sequence from $[\Phi(f_0 \ldots f_{u-1})]$ to $[\Phi(g_0 \ldots g_{v-1})]$ followed by the cost of inserting $g_{v-1}$ by a normal insert operator.

\[\square\]