

# The Computation of Elementary Unitary Matrices

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## Abstract

The construction of elementary unitary matrices that transform a complex vector to a real multiple of  $e_1$ , the first column of the identity matrix, are studied. We survey the two well known forms and present what appears to be relatively unknown third form implemented by LAPACK subroutine CLARFG.

## 1 Introduction

Define the elementary Hermitian (or unitary) matrix

$$U = I - 2ww^H, \quad (1)$$

where  $w^H w = 1$ . Easily verified is that  $U$  is both Hermitian and unitary and is also referred to as a Householder matrix. The matrix  $U$  as defined by (1) is a special case of the more general class of *elementary* matrices defined by

$$E(u, v; \sigma) = I - \sigma uv^H. \quad (2)$$

See [2], [3] and [4] for further details. The latter reference is a comprehensive study of elementary matrices, their properties and extensions to *block* implementations.

In [3] Wilkinson states that it is not possible, in general, to find an elementary matrix  $U$  such that

$$Ux = \alpha e_1, \quad (3)$$

for a complex vector  $x$  with  $\alpha$  a real number. Note that  $U$  is unitary implies that  $|\alpha| = \|x\|_2$ . If the above relation were satisfied then

$$x^H \alpha e_1 = x^H Ux.$$

The righthand side is a real number since  $U$  is Hermitian. But if  $e_1^T x$  has a non-zero imaginary part we have a contradiction. The necessary condition is that  $x^H e_1 = e_1^T x$ . Equivalently  $e_1^T x = \xi_1$  must have zero imaginary part.

The purpose of this note is to review and examine the case of constructing elementary unitary matrices that satisfy (3) for a complex vector  $x$ . The next section

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discusses the approach suggested by Wilkinson. The third section introduces yet another approach due to Hammarling and Du Croz. It has been implemented in the NAG Fortran Library subroutine F06HRF, see [1]. A slightly different implementation is the LAPACK subroutine CLARFG. The details of the software implementation for CLARFG are in section four. In fact what led to this study is attempting to understand the differences between the Wilkinson approach and the alternate formulation implemented by LAPACK, [6]. Section five generalizes the Hammarling–Du Croz form for transforming a complex vector  $x$  into another complex vector  $y$ . The last section contains the source code for subroutine CLARFG.

## 2 The Wilkinson Approach

Wilkinson suggests the following modification in Chapter 2, section 45 of [3]. If  $e_1^T x = \xi_1$  has non-zero imaginary part then

$$\begin{aligned} x &= e^{i\theta_1} [|\xi_1|, e^{-i\theta_1} \xi_2, \dots, e^{-i\theta_1} \xi_n]^T, \\ &= e^{i\theta_1} y, \end{aligned}$$

where  $e^{i\theta_1} |\xi_1|$  is the polar form for  $\xi_1$ . Since  $e_1^T y$  is a real number, a Householder matrix  $P$  may be constructed satisfying (3). Set  $U = e^{-i\theta_1} P$  and

$$\begin{aligned} Ux &= e^{-i\theta_1} Px, \\ &= e^{-i\theta_1} P e^{i\theta_1} y, \\ &= Py, \\ &= \alpha e_1. \end{aligned}$$

The matrix  $U$  is not Hermitian but is unitary which is the crucial property. The value of  $\alpha$  is not affected;

$$\begin{aligned} |\alpha| &= \|Ux\|_2, \\ &= |e^{-i\theta_1}| \|Px\|_2, \\ &= \|x\|_2. \end{aligned}$$

The matrix  $U$  constructed is not an elementary matrix. If  $\xi_1$  is real then  $\theta_1$  is arbitrary and may be chosen equal to zero. The resulting elementary matrix is then also Hermitian.

The Wilkinson approach is used by LINPACK when working with complex data.

## 3 An Alternate Approach

The final form for an elementary unitary matrix studied is due to Hammarling and Du Croz, see [1] (Introduction – F06). We now derive this alternate form. Consider the general form (2) for an elementary unitary matrix  $U = E(u, v; \sigma)$ . The matrix must be unitary from which it follows that

$$\begin{aligned} I &= U^H U, \\ &= (I - \sigma uv^H)^H (I - \sigma uv^H), \\ &= I - \bar{\sigma} v u^H - \sigma uv^H + \sigma \bar{\sigma} (u^H u) v v^H, \end{aligned}$$

and cancelling terms results in

$$\sigma \bar{\sigma} (u^H u) v v^H = \bar{\sigma} v u^H + \sigma u v^H. \quad (4)$$

Rearranging terms gives

$$(\sigma \bar{\sigma} (u^H u) v - \sigma u) v^H = \bar{\sigma} v u^H,$$

and a row space argument implies that  $u$  and  $v$  are linearly dependent. Substituting  $u = v$  into (4) results in

$$\begin{aligned} |\sigma|^2 \|v\|_2^2 &= \sigma + \bar{\sigma}, \\ &= 2\operatorname{Re}(\sigma), \end{aligned} \quad (5)$$

determining the required relationship between  $\sigma$  and  $v$ . Choosing  $v = x - \alpha e_1$  we have

$$\begin{aligned} Ux &= (I - \sigma v v^H)x, \\ &= x - (\sigma v^H x)v, \\ &= \alpha e_1, \end{aligned}$$

if  $\sigma^{-1} = v^H x$ . This choice of  $\sigma$  will satisfy (5) as we now demonstrate. First

$$\begin{aligned} v^H x &= (x^H - \alpha e_1^T)x, \\ &= x^H x - \alpha \xi_1, \\ &= \alpha(\alpha - \xi_1), \end{aligned}$$

which determines  $\sigma$  and

$$\begin{aligned} \|v\|_2^2 &= v^H v, \\ &= (x^H - \alpha e_1^T)(x - \alpha e_1), \\ &= 2\alpha(\alpha - \operatorname{Re}(\xi_1)), \end{aligned}$$

follows. Finally

$$\begin{aligned} (v^H x)(x^H v)(\sigma + \bar{\sigma}) &= (v^H x)(x^H v)\left(\frac{1}{v^H x} + \frac{1}{x^H v}\right), \\ &= x^H v + v^H x, \\ &= \alpha(\alpha - \xi_1) + \alpha(\alpha - \bar{\xi}_1), \\ &= 2\alpha(\alpha - \operatorname{Re}(\xi_1)), \end{aligned}$$

shows

$$\frac{\sigma + \bar{\sigma}}{|\sigma|^2} = \|v\|_2^2,$$

as claimed. The form as outlined in this section does not appear to be as widely known as the Wilkinson one. It has the benefit of transforming a complex vector  $x$  directly to real multiple of  $e_1$ . When  $\xi_1$  is purely real then  $U$  is Hermitian. Unlike the Wilkinson variant the Hammarling–Du Croz approach results in an elementary unitary matrix.

## 4 Software Implementation of CLARFG

The actual implementation of the Hammarling–Du Croz variant has some slight modifications. The resulting code is an excellent example of the art of developing software from a numerical algorithm. Subroutine CLARFG determines an elementary unitary matrix  $U = I - \tau uu^H$  such that  $U^H x = \alpha e_1$  where  $|\alpha| = \|x\|_2$  for  $\alpha$  a real number. Simplifying the implementation of other algorithms in LAPACK requiring the use of elementary unitary matrices the normalization  $u^H e_1 = 1$  is taken. This normalization is done for storage considerations and is discussed in [5]. From the previous section it follows that

$$\begin{aligned} U^H &= I - \frac{1}{\alpha(\alpha - \bar{\xi}_1)} vv^H, \\ &= I - \frac{(\xi_1 - \alpha)(\bar{\xi}_1 - \alpha)}{\alpha(\alpha - \bar{\xi}_1)} uu^H, \\ &= I - \frac{\alpha - \xi_1}{\alpha} uu^H, \\ &= I - \tau uu^H, \end{aligned}$$

where

$$\begin{aligned} u &= \frac{v}{\xi_1 - \alpha}, \\ &= \frac{x - \alpha e_1}{\xi_1 - \alpha}, \end{aligned}$$

and

$$\tau = \frac{\alpha - \xi_1}{\alpha}.$$

Storage of  $U$  for use in further computation only requires storage for the complex  $\tau$  and  $x$  may be overwritten with both  $\alpha$  and the *essential* part of  $u$ , i.e.

$$x \leftarrow \left[ \alpha, \frac{\xi_2}{\xi_1 - \alpha}, \dots, \frac{\xi_n}{\xi_1 - \alpha} \right]^T.$$

In order that the value for  $\tau$  and the scaling factor  $\xi_1 - \alpha$  have small relative error

$$\alpha \leftarrow -\text{sign}(\text{Re}(\xi_1)) \|x\|_2,$$

is chosen. This is a standard modification and is mentioned for the sake of completeness. The resulting  $\tau$  satisfies the two properties

$$\begin{aligned} 1 &\leq \text{Re}(\tau) \leq 2, \\ |\tau - 1| &\leq 1, \end{aligned}$$

when  $x \neq \gamma e_1$  with  $\gamma$  real. If  $x$  is a real multiple of  $e_1$  then set

$$\begin{aligned} \tau &\leftarrow 0, \\ U &\leftarrow I. \end{aligned}$$

The reviewer of CLARFG will notice one final point which needs explanation. The careful programmer took care not to reciprocate the number  $\|x\|_2$  that may fall below a certain machine dependent tolerance, SAFMIN. The value SAFMIN, computed by the LAPACK auxiliary subroutine SLAMCH is a machine dependent lower bound for numbers that may be safely reciprocated and not cause an overflow condition. If  $\|x\|_2$  is less than the lower bound then the vector  $x$  is scaled by a multiple of the reciprocal of SAFMIN until  $\|\theta x\|_2$  is at least as large as SAFMIN. Defining the integer  $k$  to represent the number of scalings required results in

$$\theta = k \frac{1}{\text{SAFMIN}}.$$

The number  $\tau$  may now be safely computed as

$$\tau \leftarrow \frac{\|\theta x\|_2 - \theta \xi_1}{\|\theta x\|_2}.$$

In a similar fashion

$$\alpha \leftarrow -\text{sign}(\text{Re}(\xi_1)) \frac{1}{\theta} (\|\theta x\|_2),$$

and the essential part of  $u$

$$u \leftarrow \frac{1}{\theta \xi_1 - \theta \alpha} [\theta \xi_2, \dots, \theta \xi_n]^T,$$

are computed.

## 5 Generalizations

We conclude with the problem of determining an elementary unitary matrix  $U$  that satisfies

$$\begin{aligned} Ux &= (I - \sigma v v^H)x, \\ &= y, \end{aligned} \tag{6}$$

where  $\|x\|_2 = \|y\|_2$ . The derivation of section three requires little modification. The value of  $\sigma^{-1} = v^H x$  and

$$\begin{aligned} v &= x - y, \\ v^H x &= \|x\|_2^2 - y^H x, \end{aligned}$$

may be shown to satisfy (5) and (6).

## 6 Acknowledgements

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## References

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- [3] J. H. Wilkinson, *The Algebraic Eigenvalue Problem*, Clarendon Press, Oxford, UK, 1965.
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- [6] E. Anderson, Z. Bai, C. Bischoff, J. Demmel, J. Dongarra, J. Du Croz, A. Greenbaum, S. Hammarling, A. McKenney, S. Ostrouchov, and D. C. Sorensen, *LAPACK Users' Guide*, SIAM, 1992.
- [7] J. J. Dongarra, C. B. Moler, J. R. Bunch, G. W. Stewart, *LINPACK Users' Guide*, SIAM, 1979.

## 7 LAPACK Subroutine CLARFG

```

SUBROUTINE CLARFG( N, ALPHA, X, INCX, TAU )
*
*  -- LAPACK auxiliary routine (version 1.1) --
*  Univ. of Tennessee, Univ. of California Berkeley, NAG Ltd.,
*  Courant Institute, Argonne National Lab, and Rice University
*  February 29, 1992
*
*  .. Scalar Arguments ..
      INTEGER          INCX, N
      COMPLEX          ALPHA, TAU
*
*  .. Array Arguments ..
      COMPLEX          X( * )
*
*  ..
*
* Purpose
* =====
*
* CLARFG generates a complex elementary reflector H of order n, such
* that
*
*      H' * ( alpha ) = ( beta ),   H' * H = I.
*           (  x  )   (  0  )
*
*
```

```

* where alpha and beta are scalars, with beta real, and x is an
* (n-1)-element complex vector. H is represented in the form
*
*      H = I - tau * ( 1 ) * ( 1 v' ) ,
*                   ( v )
*
* where tau is a complex scalar and v is a complex (n-1)-element
* vector. Note that H is not hermitian.
*
* If the elements of x are all zero and alpha is real, then tau = 0
* and H is taken to be the unit matrix.
*
* Otherwise 1 <= real(tau) <= 2 and abs(tau-1) <= 1 .
*
* Arguments
* =====
*
* N          (input) INTEGER
*           The order of the elementary reflector.
*
* ALPHA      (input/output) COMPLEX
*           On entry, the value alpha.
*           On exit, it is overwritten with the value beta.
*
* X          (input/output) COMPLEX array, dimension
*           (1+(N-2)*abs(INCX))
*           On entry, the vector x.
*           On exit, it is overwritten with the vector v.
*
* INCX       (input) INTEGER
*           The increment between elements of X. INCX <> 0.
*
* TAU        (output) COMPLEX
*           The value tau.
*
* =====
*
* .. Parameters ..
* REAL       ONE, ZERO
* PARAMETER  ( ONE = 1.0E+0, ZERO = 0.0E+0 )
*
* ..
*
* .. Local Scalars ..
* INTEGER    J, KNT
* REAL       ALPHI, ALPHR, BETA, RSAFMN, SAFMIN, XNORM
*
* ..
*
* .. External Functions ..
* REAL       SCNRM2, SLAMCH, SLAPY3

```

```

COMPLEX          CLADIV
EXTERNAL         CLADIV, SCNRM2, SLAMCH, SLAPY3
*
* ..
* .. Intrinsic Functions ..
INTRINSIC        ABS, AIMAG, CMLPX, REAL, SIGN
*
* ..
* .. External Subroutines ..
EXTERNAL         CSCAL, CSSCAL
*
* ..
* .. Executable Statements ..
*
IF( N.LE.0 ) THEN
    TAU = ZERO
    RETURN
END IF
*
XNORM = SCNRM2( N-1, X, INCX )
ALPHR = REAL( ALPHA )
ALPHI = AIMAG( ALPHA )
*
IF( XNORM.EQ.ZERO .AND. ALPHI.EQ.ZERO ) THEN
*
*     H = I
*
*     TAU = ZERO
ELSE
*
*     general case
*
    BETA = -SIGN( SLAPY3( ALPHR, ALPHI, XNORM ), ALPHR )
    SAFMIN = SLAMCH( 'S' )
    RSAFMN = ONE / SAFMIN
*
    IF( ABS( BETA ).LT.SAFMIN ) THEN
*
*         XNORM, BETA may be inaccurate; scale X and recompute them
*
*
*         KNT = 0
10      CONTINUE
*         KNT = KNT + 1
*         CALL CSSCAL( N-1, RSAFMN, X, INCX )
*         BETA = BETA*RSAFMN
*         ALPHI = ALPHI*RSAFMN
*         ALPHR = ALPHR*RSAFMN
*         IF( ABS( BETA ).LT.SAFMIN )
$           GO TO 10
*
*

```



```

*           New BETA is at most 1, at least SAFMIN
*
      XNORM = SCNRM2( N-1, X, INCX )
      ALPHA = CMPLX( ALPHR, ALPHI )
      BETA = -SIGN( SLAPY3( ALPHR, ALPHI, XNORM ), ALPHR )
      TAU = CMPLX( ( BETA-ALPHR ) / BETA, -ALPHI / BETA )
      ALPHA = CLADIV( CMPLX( ONE ), ALPHA-BETA )
      CALL CSCAL( N-1, ALPHA, X, INCX )
*
*           If ALPHA is subnormal, it may lose relative accuracy
*
      ALPHA = BETA
      DO 20 J = 1, KNT
        ALPHA = ALPHA*SAFMIN
20    CONTINUE
      ELSE
        TAU = CMPLX( ( BETA-ALPHR ) / BETA, -ALPHI / BETA )
        ALPHA = CLADIV( CMPLX( ONE ), ALPHA-BETA )
        CALL CSCAL( N-1, ALPHA, X, INCX )
        ALPHA = BETA
      END IF
    END IF
*
  RETURN
*
*           End of CLARFG
*
  END

```